## TA-Slider 1600



## Actuators

Digitally configurable proportional push-pull actuator

- 1600 N


## TA-Slider 1600

Digitally configurable actuators for all control systems with or without Bus communication. Wide range of setup possibilities gives high flexibility to adapt parameters on-site. Fully programmable binary input, relay and adjustable max. stroke of the valve bring new opportunities for advanced hydronic control and balancing.

## Key features

## $>$ Convenient, reliable setup

Fully customisable by smartphone via Bluetooth using a TA-Dongle.

Fully configurable
More than 200 setup options allow input and output signals, binary input, relay, characteristics and many other parameters to be configured.

## Easy diagnostics

Tracks the last 10 errors to allow system faults to be found quickly.

## $>$ Perfection in connectivity

Communication with the most used Bus protocols.


## Technical description

## Functions:

Proportional control
3 -point control
On-off control
Manual override
Stroke detection
Mode, status and position indication
Output signal VDC
Stroke limitation setting
Minimum stroke setting
Valve blockage protection
Valve clogging detection
Error safe position
Diagnostic/Logging
Delayed start-up
Plus version:
With optional Bus communication board

+ ModBus or BACnet
With optional relay board
+1 binary input, max. $100 \Omega$, cable max. 10 m or shielded.
+2 relays, max. 5A, 30 VDC/250 VAC on resistive load
+ Output signal in mA


## Supply voltage:

24 VAC/VDC $\pm 15 \%$.
$100-240$ VAC $\pm 10 \%$.
Frequency $50 / 60 \mathrm{~Hz} \pm 3 \mathrm{~Hz}$.

## Power consumption:

24 VAC/VDC:
Operation: < 11.5 VA (VAC); < 5.7 W (VDC)
Standby: < 1.1 VA (VAC); < 0.5 W (VDC)
100-240 VAC:
Operation: < 11.8 VA (VAC)
Standby: < 1.7 VA (VAC)

## Input signal:

$0(2)-10 \mathrm{VDC}, \mathrm{R}_{1} 47 \mathrm{k} \Omega$.
Adjustable sensitivity 0.1-0.5 VDC.
0.33 Hz low pass filter.
$0(4)-20 \mathrm{mAR}, 500 \Omega$.
Proportional:
0-10, 10-0, 2-10 or 10-2 VDC
$0-20,20-0,4-20$ or 20-4 mA
Proportional split-range:
$0-5,5-0,5-10$ or 10-5 VDC
$0-4.5,4.5-0,5.5-10$ or 10-5.5 VDC
2-6, 6-2, 6-10 or 10-6 VDC
0-10, 10-0, 10-20 or 20-10 mA
$4-12,12-4,12-20$ or 20-12 mA
Proportional dual-range (for change-over):
0-3.3 / 6.7-10 VDC,
10-6.7 / 3.3-0 VDC,
2-4.7 / 7.3-10 VDC or
10-7.3 / 4.7-2 VDC.
Default setting: Proportional 0-10 VDC.

## Output signal:

$0(2)-10 \mathrm{VDC}$, max. 8 mA , min. $1.25 \mathrm{k} \Omega$.
Plus version:
$0(4)-20 \mathrm{~mA}, \max .700 \Omega$.
Ranges: See "Input signal".
Default setting: Proportional 0-10 VDC.

## Characteristics:

Linear, EQM 0.25 and inverted EQM 0.25 .
Default setting: Linear.

## Control speed:

$3,4,6,8,12$ or $16 \mathrm{~s} / \mathrm{mm}$
Default setting: $3 \mathrm{~s} / \mathrm{mm}$.

## Adjusting force:

## 1600 N

## Temperature:

Media temperature: $0^{\circ} \mathrm{C}-+120^{\circ} \mathrm{C}$
Operating environment: $0^{\circ} \mathrm{C}-+50^{\circ} \mathrm{C}$ (5-95\%RH, non-condensing)
Storage environment: $-20^{\circ} \mathrm{C}-+70^{\circ} \mathrm{C}$ (5-95\%RH, non-condensing)

## Ingress protection:

IP 54 (all directions)
(according to EN 60529)

## Protection class:

(according to EN 61140).
100-240 VAC: Class I.
24 VAC/VDC: Plus version with optional relay board, Class I. All other versions, Class III safety extra low voltage.

## Stroke:

Max. 33 mm
Automatic detection of the valve lift (stroke detection).

## Noise level:

Max. 40 dBA

## Weight:

$1,6 \mathrm{~kg}$

## Connection to valve:

By two M8 screws to the valve and by quick connection to the stem.

## Material:

Cover: PBT
Bracket: Alu EN44200

## Colour:

Orange RAL 2011, grey RAL 7043.

## Marking:

IMI TA, product name, article No. and technical specification.
LED indication description.

## Certification CE:

LV-D. 2014/35/EU: EN 60730-1, -2-14. EMC-D. 2014/30/EU: EN 60730-1, -2-14. RoHS-D. 2011/65/EU: EN 63000.

## Product standard:

EN 60730.
(for Residential and industrial areas)

## Cable:

Wire cross-section*: $0.5-2.0 \mathrm{~mm}^{2}$ Protection class I: H05W-F or similar Protection class III: LiYY or similar
*) Note: Wire cross-sections must be chosen according to actuator power consumption and line length, such as the voltage supply to the actuator does not go below 20.4 VAC/VDC ( 24 VAC/VDC minus 15\%).
In case of VDC input signal on a $24 \mathrm{VAC} /$ VDC powered actuator, the voltage drop on neutral line must be smaller than the defined hysteresis level for the VDC input signal.

## Function

## Setting

The actuator can be set by the HyTune app (iOS version 8 or later on iPhone 4S or later, Android version 4.3 or later) + the TA-Dongle device, with or without the actuator power supplied. The setting configuration can be stored in the TA-Dongle for setting of one or several actuators. Connect the TA-Dongle to the actuator and press the configuration button. HyTune can be downloaded from the App Store or Google Play.


## Setting Bus communication parameters

Configuration of Bus parameters such as address, baud rate, parity and more is to be carried out by the HyTune app + the
TA-Dongle device, with or without the actuator power supplied. More detailed information, please see Bus protocol implementation documents.

## Manual override

By 5 mm Allen key or by the TA-Dongle device.
Note: Power supply needed when TA-Dongle is used.

## Position indicator

Visible mechanical stroke indication on the bracket.
Calibration/Stroke detection
According to selected settings in the table.

| Type of calibration | At power on | After manual <br> override |
| :--- | :---: | :---: |
| Both end positions (full) | $\checkmark$ * | $\checkmark$ |
| Fully extended position (fast) | $\checkmark$ | $V^{\star}$ |
| None | $\checkmark$ |  |

*) Default
Note: A calibration refresh can be automatically repeated monthly or weekly.
Default setting: Off.

## Stroke limitation setting

A maximum stroke smaller than or equal to the detected valve lift can be set to the actuator.
For some TA/HEIMEIER valves it can also be set to a $\mathrm{Kv}_{\max } / \mathrm{a}_{\max }$. Default setting: No stroke limitation (100\%).

## Minimum stroke setting

The actuator can be set with a minimum stroke below which it will not go (except for calibration).
For some TA/HEIMEIER valves, it can also be set to a qmin. Default setting: No minimum stroke (0\%).

## Valve blockage protection

The actuator will perform a quarter of a full stroke and then back to desired value if no actuation takes place for one week or one month.
Default setting: Off.

## Valve clogging detection

If actuation stops before the desired value is reached, the actuator moves back ready to make a new attempt. The actuator will move to the configured error safe position after three attempts.
Default setting: On.

## Error safe position

Fully extended or retracted position when following errors occur; low power, line break, valve clogging or stroke detection failure. Default setting: Fully extended position.

## Diagnostics/logging

The last 10 errors (low power, line break, valve clogging, stroke detection failure) with time stamps can be read using the HyTune app + TA-Dongle device. Logged errors will be cleared if the power is disconnected.

## Delayed start-up

The actuator can be specified a delay ( 0 to 1275 sec.) before starting up after a power supply cut. This is useful when used with a control system that has itself a long start-up time.
Default setting: 0 seconds.

## Plus version:

## Connection interfaces for Bus communication

- RS485; BACnet MS/TP, Modbus/RTU
- Ethernet; BACnet/IP, Modbus/TCP


## Binary input

If the binary input circuit is open, the actuator will go to a set stroke, switch to a second stroke limitation setting or drive to its full stroke regardless of any limitations for flushing purpose. See also Change-over system detection.
Default setting: Off

## Change-over system detection

Switching between two different stroke limitation settings by toggling the binary input or using the dual-range input signal. For the Bus versions, this switching may also be made via the Bus.

## LED indication

|  |  | Status | Green |
| :---: | :---: | :---: | :---: |
| $\triangle$ |  | Fully retracted（actuator stem） | Long pulse－Short pulse |
|  |  | Fully extended（actuator stem） | Short pulse－Long pulse |
|  | $\square \longrightarrow$ | Intermediate position | Long pulses |
|  |  | Moving | Short pulses |
| ， | －－－－－ | Calibrating | 2 short pulses |
| （0）＝－ $\mathrm{Mr}^{\text {a }}$ |  | Manual mode or no power supply | Off |


|  |  | Error code | Red |
| :---: | :---: | :---: | :---: |
| $\sim /=0$ | －－－ | Power supply too low | 1 pulse |
| $\bigotimes^{+} f+$ | － | Line broken（2－10 V or 4－20 mA） | 2 pulses |
| $4 \square \bigcirc$ |  | Valve clogging or foreign object | 3 pulses |
|  | －ーツー－－ | Stroke detection failure | 4 pulses |

If an error is detected，red pulses are displayed as the green status lights flash alternately． More detailed information，please see the HyTune app＋TA－Dongle．


## Installation



## Connection diagram - Terminal/Description

| Terminal | Description |
| :---: | :---: |
| L24 | Power supply 24 VAC/VDC |
| M* | Neutral for power supply 24 VAC/NDC and signals |
| L | Power supply 100-240 VAC |
| N | Neutral for power supply 100-240 VAC |
| $Y_{i}$ | Input signal for proportional control 0(4)-20 mA, $500 \Omega$ |
| $Y_{v}$ | Input signal for proportional control $0(2)-10 \mathrm{VDC}, 47 \mathrm{k} \Omega$ |
| ${ }_{1}$ | Output signal 0(4)-20 mA, max. resistance $700 \Omega$ |
| $\mathrm{X}_{\mathrm{v}}$ | Output signal 0(2)-10 VDC, max. 8 mA or min. load resistance $1.25 \mathrm{k} \Omega$ |
| Dw | 3 -point control signal for extending actuator spindle (24 VACNDC or 100-240 VAC) |
| Up | 3 -point control signal for retracting actuator spindle (24 VAC/VDC or 100-240 VAC) |
| B | Connection for potential free contact (e.g. open window detection), max. $100 \Omega$, max. 10 m cable or shielded |
| COM1, COM2 | Common relay contacts, max. 250 VAC, max. 5A @ 250 VAC on resistive load, max. 5A @ 30 VDC on resistive load |
| NC1, NC2 | Normally closed contacts for relays 1 and 2 |
| NO1, NO2 | Normally open contacts for relays 1 and 2 |

*) All M terminals are internally connected.

## Connection diagram - 24 V




3-point


On-off


Connection diagram - 100-240 V

$0(4)-20 \mathrm{~mA}$


## On-off



Q 24 VAC/DC operating only with safety transformer according EN 61558-2-6

Connection diagram - Relay (for Plus version only)

## Optional relay board


*) Low voltage neutral
${ }^{* *}$ ) Ground connection required.

## Connection diagram - Bus communication (for Plus version only)

## Optional Ethernet communication board

BACnet/IP, Modbus/TCP


Optional RS 485 board
BACnet MS/TP, Modbus/RTU


Note: A, B, A', B' and GND terminals are isolated from all other terminals.

## Articles



TA-Slider 1600
Input signal: 0(2)-10 VDC, 0(4)-20 mA, 3-point, on-off

| Supply voltage | EAN | Article No |
| :--- | :--- | :--- |
| 24 VAC/NDC | 5902276816789 | $322228-10110$ |
| $100-240$ VAC | 5902276816796 | $322228-40110$ |

## TA-Slider 1600 Plus

Input signal: 0(2)-10 VDC, 0(4)-20 mA, 3-point, on-off
With binary input, relays, mA output

| Supply voltage | Bus | EAN | Article No |
| :--- | :--- | :--- | :--- |
| 24 VACNDC | - | 5902276816802 | $322228-10219$ |
| $100-240$ VAC | - | 5902276816819 | $322228-40219$ |

With BUS communication (without binary input, relays, mA output)

| Supply voltage | Bus |  | EAN | Article No |
| :--- | :--- | :--- | :--- | :--- |
| 24 VAC/NDC | Modbus/RTU | RS 485 | 5902276816826 | $322228-12210$ |
|  | BACnet MS/TP | RS 485 | 5902276816833 | $322228-13210$ |
|  | Modbus/TCP | Ethernet | 5902276816840 | $322228-14210$ |
|  | BACnet/IP | Ethernet | 5902276816857 | $322228-16210$ |
| $100-240$ VAC |  |  |  |  |
|  | Modbus/RTU | RS 485 | 5902276816864 | $322228-42210$ |
|  | BACnet MS/TP | RS 485 | 5902276816871 | $322228-43210$ |
|  | Modbus/TCP | Ethernet | 5902276816888 | $322228-44210$ |
|  | BACnet/IP | Ethernet | 5902276816895 | $322228-46210$ |

With BUS communication, binary input, relays, mA output

| Supply voltage | Bus |  | EAN | Article No |
| :--- | :--- | :--- | :--- | :--- |
| 24 VAC/NDC | Modbus/RTU | RS 485 | 5902276816901 | $322228-12219$ |
|  | BACnet MS/TP | RS 485 | 5902276816918 | $322228-13219$ |
|  | Modbus/TCP | Ethernet | 5902276816925 | $322228-14219$ |
|  | BACnet/IP | Ethernet | 5902276816932 | $322228-16219$ |
|  |  |  |  |  |
| $100-240$ VAC | Modbus/RTU | RS 485 | 5902276816949 | $322228-42219$ |
|  | BACnet MS/TP | RS 485 | 5902276816956 | $322228-43219$ |
|  | Modbus/TCP | Ethernet | 5902276816963 | $3222288-44219$ |
|  | BACnet/IP | Ethernet | 5902276816970 | $322228-46219$ |

## Additional equipment



## TA-Dongle

For Bluetooth communication with the
EAN
Article No
HyTune app, transfer configuration
settings and manual override.
5901688828632 322228-00001

## Accessories

## Stem heater

Including spindle top (extension) and extended screws.
Temperature range till $-10^{\circ} \mathrm{C}$.
Voltage $24 \mathrm{VAC} \pm 10 \%, 50 / 60 \mathrm{~Hz} \pm 5 \%$.
Power $P_{\mathrm{N}}$ approx. 30 W .
Current 1,4 A.
Surface temperature max. $50^{\circ} \mathrm{C}$.

| For valve | DN | L | H | W | D | EAN | Article No |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | 146 | 49 | 70 | 30 |  |  |
| KTM 512 | $65-125$ |  |  |  |  | 3831112533455 | $322042-81401$ |
| TA-Modulator | $65-200$ |  |  |  |  | 3531112534834 | $322042-80010$ |

